#### CSE6243: Advanced Machine Learning

Lecture 16: EBMs, GANs, and Divergences

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Fall 2023

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## 16.1 Recap

EBM: Energy-based Model:

$$\frac{\exp(g_0|x)}{Z_0}, Z_0 = \int \exp(g_0|x)$$

Autoregressive model (combine Transformer in ChatGPT):

$$P\left(\{x_i\}_{i=1}^d\right) = \prod_{i=1}^d P\left(x_i | x_{< i}\right)$$

This model generates probabilities at a location as a function of all the values before it.

VAE (latent model):

$$P_{\theta}(x) = \int P_{\theta}(x|z)P(z)dz,$$

Here, we explicitly find the latent space and classify each data point by generating a probability through integration over the whole latent space.

Diffusion model (image/video modeling):

$$P_{\theta}(x) = \int P_{\theta}(x|z_0) \prod_{i=1}^{k} p(z_{i-1}|z_i) dz_{i=0}^{k}$$

We combine aspects of VAEs and autoregressive models by generating probabilities through integrating across all paths of diffusion timesteps

## 16.2 New Content

### 16.2.1 Generative Adversarial Net(GAN)

Generative Adversarial Net(GAN) learns samplers instead of explicitly learning distribution. This could be turned to

$$\varepsilon \sim P(\varepsilon), \quad N(0, \theta^{i}I) | x = g_{\theta}(\varepsilon_{i})$$

which generates samples as a function of random noise  $\epsilon$ .

Objective function: Represents a generator network trying to minimize loss and discriminator network trying to maximize loss.

$$\min_{\theta} \max_{\phi} \mathcal{L}(\theta, \phi) = \mathbb{E}_{P_d} \left[ \log D_{\phi}(x) \right] + \mathbb{E}_{x = g_{\theta}(x)} \left[ \log \left( 1 - D_{\phi}(x) \right) \right] \quad \leftarrow \text{MLE for logistic regression}$$

**Step 1.** Fix a  $\phi$  and  $\max D_{\phi}(x)\mathcal{L}(\phi,\theta)$  when  $\nabla_{D_{\phi}(x)}\mathcal{L}(\phi,\theta) = 0$ 

 $\Rightarrow \forall x \text{ calculate}$ 

$$\nabla_{D_{\phi}(x)} \left( P_d(x) \cdot \log D_{\phi}(x) + D_{g_{\theta}}(x) \cdot \log \left( 1 - D_{\phi}(x) \right) \right)$$
$$= P_d(x) \cdot \frac{1}{D_{\phi}(x)} - P_{g_{\theta}}(x) \cdot \frac{1}{1 - D_{\phi}(x)} = 0$$

Then,

$$D_{\phi}(x) = \frac{P_d(x)}{P_d(x) + P_{g_{\theta}}(x)}$$

#### **Step 2.** Find the optimal $\theta$ under fixed $\phi$ .

We put the  $\phi$  into the objective function.

$$\begin{split} L\left(\theta,\phi^*\right) &= \mathbb{E}_{P_d}\left[\log\cdot D^*(\phi)\right] + \mathbb{E}_{P_{g_\theta}}\left[\log\left(1 - D^*_{\phi}(x)\right)\right] \\ &= \int P_d(x) \cdot \log\frac{P_d(x)}{P_d(x) + P_{g_\theta}(x)} dx + \int P_{g_\theta}(x) \cdot \log\frac{P_{g_\theta}(x)}{P_d(x) + P_{d_\theta}(x)} dx \\ &\propto 2\mathrm{JS}\left(P_d \cdot P_{g_\theta}\right) + \mathrm{const} \end{split}$$

Recall Jensen -Shannon divergence

$$\mathrm{JS}(p,q) = \frac{1}{2}\mathrm{KL}\left(p\|\frac{p+q}{2}\right) + \frac{1}{2}\mathrm{KL}\left(q\|\frac{p+q}{2}\right)$$

Generator's goal is to minimize this divergence by recovering the original data distribution.

### Algorithm.

Init  $x = g_{\theta_0}(\varepsilon_i)$ 

For  $i = 1, \ldots, T$ 

- 1. Sample  $x \sim P_d$  take instance of real data
- 2. Sample  $x' = g_{\theta}(\varepsilon), \quad \varepsilon_i \sim P_0(\varepsilon)$
- 3. For k = 1, ..., K,  $\phi_{k+1} : \phi_k + \eta_k \hat{\nabla}_{\phi} \mathcal{L}(\theta, \phi)$  gradient descent on  $\phi$
- 4.  $\theta_{t+1} = \theta_t \lambda_t \hat{\nabla}_{\phi} L(\theta, \phi_k)$  gradient descent on  $\theta$ . Note that we don't update  $\theta$  every time we update  $\phi$ , as the two networks are adversaries, and so we need to make sure we don't simply make one better by weakening the other.

Based on JS-Divergence, we also call above algorithm as JS -GAN (minimizing JS divergence)

# 16.2.2 Introduction to *f*-GAN (min *f* divergence)

Recall f divergence:

$$D_f(p,q) = \mathbb{E}_q\left[f\left(\frac{p}{q}\right)\right] = \int q(x)f\left(\frac{p}{q}\right)dx$$

where  $f(\cdot)$  is a convex function, f(1) = 0.

## Choice for $f(\cdot)$ .

• KL-divergence

$$f(a) = a \cdot \log a \to D_f(p,q) = \int q(x) \cdot \frac{p(x)}{q(x)} \cdot \log \frac{p(x)}{q(x)} \cdot dx$$
$$= \int p(x) \cdot \log \frac{p(x)}{q(x)} dx$$

•  $\chi^2$ -divergence

$$f(a) = (a-1)^2, \quad D_f(p,q) = \int q(x) \left(\frac{p(x)}{q(x)} - 1\right)^2 dx$$
$$= \int q(x) \left[ \left(\frac{p(x)}{q(x)}\right)^2 - 2\frac{p(x)}{q(x)} + 1 \right] dx$$
$$= \int q(x) \left(\frac{p(x)}{q(x)}\right)^2 dx - \underbrace{\int 2 \cdot p(x) dx + \int q(x) dx}_{=-2+1=-1}$$
$$= \int q(x) \cdot \left(\frac{p(x)}{q(x)}\right)^2 dx - 1$$

• TV

$$f(a) = |a - 1|, \quad D_f(p, q) = \int |p(x) - q(x)| dx$$

We have several background knowledge for f-GAN:

### (1) $f(\cdot)$ convex

(2) The convex conjugate of a function satisfies the property f \* \*(x) = f(x). The convex conjugae is defined as f(x) where

$$f^*(y) = \sup_{x \in \Omega} \left( x^\top y - f(x) \right)$$

e.g.

$$f(x) = \frac{1}{2}x^{2}, \quad f^{*}(y) = \sup_{x} x^{\top}y - \frac{1}{2}x^{2} = y^{\top}y - \frac{1}{2}y^{\top}y = \frac{1}{2}y^{\top}y$$
$$x^{*} = y$$
$$f(x) = \log \sum_{i=1}^{n} \exp(x_{i}) \quad f^{*}(y) = \sum_{i=1}^{n} y_{i} \log y_{i}$$

Using the second property:

$$(f^*)^* x = f(x) \Rightarrow f(x) = \max_y y^\top x - f^*(y)$$

using convex conjugate in f-GAN

$$D_f(p,q) = \int q(x) \cdot f\left(\frac{p(x)}{q(x)}\right) dx = \int q(x) \sup_{y_x} \left[yx^\top x - f^*\left(y_x\right)\right] dx$$

denote  $y_x = y(x)$ , then

$$= \max_{y(x)} \int q(x) \left[ y(x)^{\top} \frac{p(x)}{q(x)} - f^*(y(x)) \right] dx$$
  
$$= \max_{y(x)} \left( \int y(x) \cdot p(x) dx - \int q(x) \cdot f^*(y(x)) dx \right)$$
  
$$= \max_{D(x)} \mathbb{E}_{p(x)} [D(x)] - \mathbb{E}_{q(x)} \cdot [f^*(D(x))]$$

# 16.2.3 Connection between EBM and GAN

EBM:

$$P_{\phi}(x) = \frac{\exp\left(D_{\phi}(x)\right)}{z(\phi)} \Rightarrow \text{MLE} = E_{P_x}\left[D_{\phi}(x)\right] - \log z(\phi), z(\phi) = \int \exp(D_{\phi}(x)dx) dx$$

Apply log and rewrite  $z(\phi)$ ,

$$\log z(\phi) = \log \int \exp\left(D_{\phi}(x)\right) dx = \sup_{q} \left\langle q(x) \cdot D(x) \right\rangle - \underbrace{\int q(x) \cdot \log q(x) dx}_{+H(q)}$$

using convex conjugate property

Then

$$\text{MLE} = \max_{\phi} \min_{q} \mathbb{E}_{P_d}[D(x)] - \mathbb{E}_q[D(x)] - H(q)$$

where H(q) is entropy.